

```

>> clear all
>> % Crea los datos de la apertura y lee los del escenario de sou_m2
>> array_m2
-----
The number of snapshots is...5000
The number of sources is...3
Source #1--> 10dB 0 ° elevation 0 ° azimuth
Source #2--> 20dB 70 ° elevation 100 ° azimuth
Source #3--> 20dB 30 ° elevation 330 ° azimuth
The number of sensors is...18
>> % Calcula los snapshots. Los guarda en un fichero .mat si se desea.
>> % Siempre guarda la matriz de covarianza estimada cov y la misma matriz
>> % sin la deseada, que se asume la primera fuente listada en sou_m2.
>> % Se generan 5000 snapshots, asi pues, tardara y, si se activa el guardar
>> % los snapshots ocupara bastante memoria.
>> mp2
-----
The number of snapshots is...5000
The number of sources is...3
Source #1--> 10dB 0 ° elevation 0 ° azimuth
Source #2--> 20dB 70 ° elevation 100 ° azimuth
Source #3--> 20dB 30 ° elevation 330 ° azimuth
The number of sensors is...18
The snapshots are not saved, just the covariance
Cov estimate in matrix cov and exact covariance in ecov saved in file cov2.mat
Cov estimate without the first source contribution saved as covn in file covn2.mat
>> %Usara la matriz cov que grabo con mp2.m. El vector apat=[1 1 0 0] activa las
>> %dos primeras opciones: Quiescent y optimo. Usa los programas dib_mal2 y
>> % pattern2.
>> mi_beam2
File mp2.m defines the scenario to be used in this program
-----
The number of snapshots is...5000
The number of sources is...3
Source #1--> 10dB 0 ° elevation 0 ° azimuth
Source #2--> 20dB 70 ° elevation 100 ° azimuth
Source #3--> 20dB 30 ° elevation 330 ° azimuth
The number of sensors is...18
    Slowness/Azimuth polar scanning data
s/a of the desired 0,0
Full size s/a plot
S/A north-east 90° elevation 45° azimuth
S/A north-west 90° elevation -45° azimuth
S/A south-west 90° elevation -135° azimuth
S/A north-east 90° elevation 135° azimuth
quiescent response
Optimum as rx-1*sd
>>

```